

# Extremal Widths on Homogeneous Groups

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We define the extremal length and extremal width of horizontal vector measures on homogeneous groups and study capacities and modules associated with sub-elliptic equations. Coincidence between various modules of horizontal vector measure systems and some specific definitions of capacity is proved. As an application we deduce a reciprocal relation between the  $p$ -capacity and the  $q$ -module,  $1/p + 1/q = 1$ .

*Keywords:* Homogeneous groups; Carnot–Carathéodory metric; Extremal length; Extremal width; Vector measures;  $p$ -module of a family of curves

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## 1. INTRODUCTION

The concept of extremal length and the module of a family of curves goes back to Grötzsch, Beurling, Ahlfors [1, 20]. In 1957 Fuglede [17] introduced the  $p$ -module of a measure system. These notions play an important role and have a lot of applications in analysis and potential theory. An interest to non-linear elliptic equations has inspired a more general notion of the module of a family of curves and the capacity associated with these types of equations [24, 25, 27, 31]. A question about the coincidence of the  $p$ -module and the  $p$ -capacity was considered in numerous papers (see, for instance, [5, 26, 39, 40, 46]). Aikawa and Ohtsuka [2] have made an effort to connect the definition of the  $p$ -capacity, associated with a linear equation of general type, to the definition of  $p$ -module of relevant vector measure systems.

Recently, the analysis of homogeneous groups (or in another terminology – Carnot groups) has been developed intensively. The fundamental role of such groups in analysis was pointed out by Stein [41, 42]. Briefly, a homogeneous group is a simply connected nilpotent Lie group, whose Lie algebra admits a grading. There is a natural family of dilations on the group under which the metric behaves like the Euclidean metric under the Euclidean dilation [9, 16]. The analysis on homogeneous groups is a test ground for the study of general sub-elliptic problems arising from vector fields

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satisfying the Hörmander hypoellipticity condition [15, 28]. An important motivation for the study of quasilinear sub-elliptic equations of the second order comes from the theory of quasiconformal and quasiregular mappings on stratified nilpotent groups [10, 19, 23, 37, 45].

In the present work, based on ideas of [2], we define a horizontal vector measure on homogeneous groups associated with linear sub-elliptic equations. The non-Riemannian geometry of the group and the structure of sub-elliptic equations introduces natural modifications. We prove some monotonicity properties of the  $p$ -module of horizontal vector measure systems. The coincidence between the  $p$ -module of measure systems and different definitions of capacity is established. As a consequence, we obtained reciprocal relationships between the  $p$ -capacity and the  $q$ -module,  $(1/p) + (1/q) = 1$ . In the next section the reader can find explicit definitions and detailed statements of main results.

**2. DEFINITIONS AND STATEMENT OF MAIN RESULTS**

Let  $\mathcal{G}$  be a Lie algebra and  $\mathbb{G}$  be a corresponding simply connected Lie group. If  $U$  and  $V$  are some sets from  $\mathcal{G}$ , then we denote by  $[U, V]$  the subspace of the algebra  $\mathcal{G}$  generated by the elements  $[X, Y] = XY - YX$ ,  $X \in U$ ,  $Y \in V$ . By induction we define the following series

$$\mathcal{G}_1 = \mathcal{G}, \quad \mathcal{G}_j = [\mathcal{G}, \mathcal{G}_{j-1}]; \quad \mathbb{G}_1 = \mathbb{G}, \quad \mathbb{G}_j = [\mathbb{G}, \mathbb{G}_{j-1}]. \tag{2.1}$$

A Lie algebra  $\mathcal{G}$  is called *nilpotent of step  $m$* , if  $\mathcal{G}_{m+1} = \{0\}$ , but  $\mathcal{G}_m \neq \{0\}$ .

We call a Lie algebra to be *graduated*, if it splits into the direct sum of vector spaces  $\mathcal{G} = V_1 \oplus V_2 \oplus \dots \oplus V_k \oplus \dots$ . Here  $[V_i, V_j] \subset V_{i+j}$ . A Lie algebra  $\mathcal{G}$  is called *stratified* if  $\mathcal{G}$  is graduated and the subspace  $V_1 \subset \mathcal{G}$  generates  $\mathcal{G}$  as an algebra according to (2.1). For the nilpotent Lie algebra  $\mathcal{G}$  of step  $m$ , we have

$$\mathcal{G} = V_1 \oplus \dots \oplus V_m; \quad [V_1, V_j] = V_{j+1}, \quad j = 1, \dots, m - 1; \quad [V_1, V_m] = \{0\}.$$

A Lie group is stratified and nilpotent if the corresponding Lie algebra is so.

A *homogeneous group*  $\mathbb{G}$  is a stratified simply connected nilpotent Lie group with the Lie algebra  $\mathcal{G}$ . Let  $X_{11}, \dots, X_{1n_1}$  be a basis of the vector space  $V_1 \subset \mathcal{G}$ ,  $n_1 = \dim V_1$ . From now on we call  $V_1$  the *horizontal space*. Since the vector fields  $X_{11}, \dots, X_{1n_1}$  generate the Lie algebra  $\mathcal{G}$ , one can choose a basis  $X_{ij}$ ,  $1 \leq j \leq n_i = \dim V_i$ ,  $1 < i \leq m$  of space  $V_i$ , such that  $X_{ij} \subset V_i$  are commutators of the vector fields  $X_{1j} \subset V_1$ ,  $j = 1, \dots, n_1$ . The collection  $X_{11}, X_{12}, \dots, X_{1n_1}$  is an example of vector fields satisfying the Hörmander hypoellipticity condition [28].

It is known [16], that if  $\mathbb{G}$  is a simply connected nilpotent Lie group with the Lie algebra  $\mathcal{G}$ , then the exponential map  $\exp : \mathcal{G} \rightarrow \mathbb{G}$  is a global diffeomorphism. Thus,  $dx \circ \exp^{-1}$  is a biinvariant Haare measure on  $\mathbb{G}$ , where  $dx$  is the Lebesgue measure on  $\mathcal{G}$ . We can identify the elements  $x \in \mathbb{G}$  of the group with the elements  $x \in \mathcal{G}$  of the algebra, and thus, with  $x \in \mathbb{R}^N$ ,  $N = \sum_{i=1}^m \dim V_i$ , by the exponential map  $x = \exp(\sum x_{ij} X_{ij})$ . The numbers  $x = (x_{ij})$ ,  $1 \leq i \leq m$ ,  $1 \leq j \leq \dim V_i = n_i$  are called the coordinates of the point  $x$ . There is a natural group of dilations, which is defined by

the rule  $\delta_r x = (r^i x_{ij})$ ,  $1 \leq i \leq m$ ,  $1 \leq j \leq n_i$ . It is easy to see that  $d(\delta_r x) = r^Q dx$ . The quantity  $Q = \sum_{i=1}^m i \cdot n_i$  is called the *homogeneous dimension* of the group  $\mathbb{G}$ .

We use the Carnot–Carathéodory metric based on the length of horizontal curves. A piecewise curve  $\gamma : [0, b] \rightarrow \mathbb{G}$  is said to be *horizontal* if its tangent vector  $\dot{\gamma}(s)$  belongs to the space  $V_1$ , i.e., there exist functions  $a_j(s)$ ,  $s \in [0, b]$ , such that

$$\sum_{j=1}^{n_1} a_j^2 \leq 1 \quad \text{and} \quad \dot{\gamma}(s) = \sum_{j=1}^{n_1} a_j(s) X_{1j}(\gamma(s)).$$

The result of [8] implies that one can connect two arbitrary points  $x, y \in \mathbb{G}$  by a horizontal curve. We fix on  $V_1$  a non-degenerate quadratic form  $\langle \cdot, \cdot \rangle$ , such that the vector fields  $X_{11}(x), \dots, X_{1n_1}(x)$  are orthonormal with respect to this form at every  $x \in \mathbb{G}$ . Then the length  $l(\gamma)$  of a curve  $\gamma$  is defined by the formula

$$l(\gamma) = \int_0^b \langle \dot{\gamma}(s), \dot{\gamma}(s) \rangle^{1/2} ds = \int_0^b \left( \sum_{j=1}^{n_1} |a_j(s)|^2 \right)^{1/2} ds.$$

The *Carnot–Carathéodory distance*  $d_c(x, y)$  is the infimum of the length over all horizontal curves connecting  $x$  and  $y \in \mathbb{G}$ . Since the quadratic form is left-invariant, the Carnot–Carathéodory metric is left-invariant as well. The group  $\mathbb{G}$  is connected, therefore the metric  $d_c(x, y)$  is finite (see [43]). For a vector  $\xi \in V_1$  we shall use the notation  $|\xi| = \langle \xi, \xi \rangle^{1/2}$ . The Hausdorff dimension of the metric space  $(\mathbb{G}, d_c)$  coincides with its homogeneous dimension  $Q$ . By  $\text{mes}(E)$  we denote the measure of the set  $E$ :  $\text{mes}(E) = \int_E dx$ . Our normalizing condition is such that the balls of radius one have the measure one:  $\text{mes}(B(0, 1)) = \int_{B(0, 1)} dx = 1$ . Since the Jacobian determinant of the dilation  $\delta_r$  is  $r^Q$ , we have that  $\text{mes}(B(\cdot, r)) = r^Q$ .

*Example 1* The Euclidean space  $\mathbb{R}^n$  with the standard structure is an example of the Abelian Carnot group: the exponential map is the identity and the vector fields  $X_{1j} = \partial/\partial x_j$ ,  $j = 1, \dots, n$ , have only trivial commutators and form the basis of the corresponding Lie algebra.

*Example 2* The simplest example of a non-abelian homogeneous group is the Heisenberg group  $\mathbb{H}^n$ . The non-commutative multiplication is defined as

$$pq = (x, y, t)(x', y', t') = (x + x', y + y', t + t' - 2xy' + 2yx'),$$

where  $\in \mathbb{R}^n$ ,  $tx, x', y, y' \in \mathbb{R}$ , and the left translation  $L_p(q) = pq$  is defined. The left-invariant vector fields

$$X_i = \frac{\partial}{\partial x_i} + 2y_i \frac{\partial}{\partial t}, \quad Y_i = \frac{\partial}{\partial y_i} - 2x_i \frac{\partial}{\partial t}, \quad i = 1, \dots, n, \quad T = \frac{\partial}{\partial t},$$

form the basis of the Lie algebra of the Heisenberg group. All non-trivial relations are of the form  $[X_i, Y_i] = -4T$ ,  $i = 1, \dots, n$ , and all other commutators vanish. Thus, the Heisenberg algebra has the dimension  $2n + 1$  and splits into the direct sum

$\mathcal{G} = V_1 \oplus V_2$ . The vector space  $V_1$  is generated by the vector fields  $X_i, Y_i, i = 1, \dots, n$ , and the space  $V_2$  is the one-dimensional center which is spanned by the vector field  $T$ .

A curve  $\gamma : I = [0, l] \rightarrow \mathbb{G}$  is called rectifiable if  $\sup\{\sum_{k=1}^p d_c(\gamma(s_k), \gamma(s_{k-1}))\}$  is finite, where the supremum ranges over all partitions  $0 = s_0 \leq s_1 \leq \dots \leq s_p = l$  of the segment  $I$ . We remark that the definition of a rectifiable curve is based on the Carnot–Carathéodory metric. That is why a curve is not rectifiable if it is not horizontal (see [29]). Thus, from now on we work only with horizontal curves.

Now we define an absolutely continuous function on curves of the horizontal fibration. For this we consider a family of horizontal curves  $\mathcal{X}$  that form a smooth fibration of an open set  $U \subset \mathbb{G}$ . Usually, one can think of a curve  $\gamma \in \mathcal{X}$  as an orbit of a smooth horizontal vector field  $X \in V_1$ . If we denote by  $\varphi_s$  the flow associated with this vector field, then the fiber is of the form  $\gamma(s) = \varphi_s(p)$ . Here the point  $p$  belongs to the surface  $S$  which is transversal to the vector field  $X$ . The parameter  $s$  ranges over an open interval  $J \in \mathbb{R}$ . One can assume that there is a measure  $d\gamma$  on the fibration  $\mathcal{X}$  of the set  $U \subset \mathbb{G}$ . The measure  $d\gamma$  on  $\mathcal{X}$  is equal to the inner product of the vector field  $X \in V_1$  and a biinvariant volume form  $dx$  (for more information see, for instance [30, 44]). The measure  $d\gamma$  satisfies the inequality

$$k_0 \text{mes}(B(x, R))^{(Q-1)/Q} \leq \int_{\gamma \in \text{mathcal{X}}, \gamma \cap B(x, R) \neq \emptyset} d\gamma \leq k_1 \text{mes}(B(x, R))^{(Q-1)/Q}$$

for sufficiently small balls  $B(x, R) \subset U$  with constants  $k_0, k_1$  which do not depend on a ball  $B(x, R)$ .

We use the symbol  $\Omega$  for a domain (open connected set) on the homogeneous group.

*Definition 2.1* A function  $u : \Omega \rightarrow \mathbb{R}, \Omega \subset \mathbb{G}$ , is said to be *absolutely continuous on lines* ( $u \in ACL(\Omega)$ ) if for any domain  $U, \bar{U} \subset \Omega$ , and any fibration  $\mathcal{X}$  defined by a left-invariant vector field  $X_{1j}, j = 1, \dots, n_1$ , the function  $u$  is absolutely continuous on  $\gamma \cap U$  with respect to the  $\mathcal{H}^1$ -Hausdorff measure for  $d\gamma$ -almost all curves  $\gamma \in \mathcal{X}$ .

The derivatives  $X_{1j}u, j = 1, \dots, n_1$ , exist almost everywhere in  $\Omega$  for such function  $u$  [30]. If they belong to  $L_p(\Omega), p \geq 1$ , for all  $X_{1j} \in V_1$ , then  $u$  is said to be from  $ACL_p(\Omega)$ .

A function  $u : \Omega \rightarrow \mathbb{R}$  is said to belong to the Sobolev space  $L_p^1(\Omega)$  if its distributional derivatives  $X_{1j}u$  along the horizontal vector fields  $X_{1j}, j = 1, \dots, n_1$ , exist, i. e., the equality  $\int_{\Omega} X_{1j}u \varphi dx = \int_{\Omega} u X_{1j}\varphi dx$  holds for all  $\varphi \in C_0^\infty(\Omega)$  and the next seminorm  $\|u\|_{L_p^1(\Omega)} = (\int_{\Omega} |\nabla_0 u|^p(x) dx)^{1/p}$  is finite. Here  $\nabla_0 u = (X_{11}u, \dots, X_{1n_1}u)$  is the *horizontal gradient* of  $u$  and  $|\nabla_0 u| = (\sum_{j=1}^{n_1} |X_{1j}u|^2)^{1/2}$ . If the function  $u$  belongs to  $L_p^1(\Omega)$ , then there exists a function  $v \in ACL_p(\Omega)$ , such that  $u = v$  almost everywhere.

Let  $\mathcal{A}(x) = (a_{ij}(x)), x \in \Omega$ , be a positive definite symmetric  $(N \times N)$ -matrix,  $N = \sum_{i=1}^m \dim(V_i)$ , with measurable components  $a_{ij}(x)$ , such that

$$\mathcal{A}(x)\eta = \sum_{j=1}^{n_1} c(x)X_{1j}(x) \quad \text{for any vector } \eta \in \mathcal{G}, \tag{2.2}$$

and

$$\alpha^{-1}|\xi| \leq \langle \mathcal{A}\xi, \mathcal{A}\xi \rangle^{1/2} = |\mathcal{A}\xi| \leq \alpha|\xi| \tag{2.3}$$

for any  $\xi \in V_1 \subset \mathcal{G}$  and some constant  $\alpha \geq 1$ . Let  $\mathcal{B}(x) = (b_{ij}(x))$  be the inverse matrix for  $\mathcal{A}(x)$ . The matrix  $\mathcal{B}(x)$  also satisfies the inequality (2.3).

We recall the definition of the  $p$ -module of a system of measures [17]. Let  $f$  be a non-negative Borel measurable function and  $\mu$  be a non-negative Borel measure. If  $\int f d\mu \geq 1$ , then we say that the function  $f$  is admissible for the measure  $\mu$ . Let  $\mathcal{E}$  be a system of non-negative Borel measures. If  $f$  is admissible for all  $\mu \in \mathcal{E}$ , then we denote by  $\mathcal{FM}(\mathcal{E})$  the set of admissible functions for the module of the system of measures  $\mathcal{E}$ . The quantity

$$M_p(\mathcal{E}) = \inf \left\{ \int f^p dx : f \geq 0, f \in \mathcal{FM}(\mathcal{E}) \right\}$$

is called the  $p$ -module of  $\mathcal{E}$ .

We define a system of vector measures on the homogeneous group, which is related to the stratified structure of the Lie algebra of  $\mathbb{G}$ . Let  $\mu = (\mu_1, \dots, \mu_{n_1})$  be a vector measure whose components  $\mu_i$  are signed measures defined for sets from  $\mathbb{G}$ . Our principal assumption is that the dimension of the vector measure is equal to  $n_1$  and coincides with the dimension of  $V_1 \subset \mathcal{G}$ , so it is natural to call this measure the *horizontal vector measure*. The total variation  $|\mu|$  of  $\mu$  is defined by

$$|\mu|(E) = \sup \sum_j |\mu(E_j)| = \sup \sum_j \left( \sum_i^{n_1} \mu_i(E_j) \right)^{1/2} \quad \text{for Borel sets } E,$$

where the supremum is taken over all finite partitions of  $E$  into Borel sets  $E_j$ . The total variation  $\mu$  is a non-negative measure. We define an exceptional set for a system of vector measures in terms of vanishing  $p$ -module of total variation of these measures.

*Definition 2.2* Let  $\mathcal{M}$  be a set of vector measures  $\mu$ . We put  $|\mathcal{M}| = \{|\mu| : \mu \in \mathcal{M}\}$ . If  $M_p(|\mathcal{M}|) = 0$ , then we say that  $\mathcal{M}$  is  $p$ -exceptional. If a statement with respect to vector measures is not satisfied only for a  $p$ -exceptional system  $\mathcal{M}$ , then we say that it holds  $p$ -almost everywhere.

We put  $K_0$  and  $K_1$  to be closed non-empty disjoint sets, such that  $K_0 \cap \overline{\Omega} \neq \emptyset$  and  $K_1 \cap \overline{\Omega} \neq \emptyset$ . The triple  $(K_0, K_1; \Omega)$  we will call the condenser.

Let  $[a, b]$  be an interval of one of the following types:  $[a, b], [a, b), (a, b],$  or  $(a, b)$ . From now on, we suppose that a horizontal curve  $\gamma : [a, b] \rightarrow \mathbb{G}$  is parameterized by the length element. We set

$$\Gamma = \Gamma(K_0, K_1; \Omega) = \left\{ \gamma : \overline{\gamma([a, b])} \cap K_i \neq \emptyset, i = 0, 1, \gamma(t) \in \Omega, t \in (a, b) \right\} \quad (2.4)$$

and call by  $\Gamma(K_0, K_1; \Omega)$  the family of curves that connect the compacts  $K_0$  and  $K_1$  in the domain  $\Omega$ .

Now we give two different definitions of  $\mathcal{A}_p$ -capacity of a condenser.

*Definition 2.3* We denote by  $\mathcal{FC}(K_0, K_1; \Omega)$  a class of functions  $u \in ACL_p(\Omega)$ , such that

$$\begin{aligned} u(x) &\longrightarrow 0 \text{ as } x \longrightarrow K_0 \cap \overline{\Omega} \quad \text{along } p\text{-almost all curves from } \Gamma(K_0, K_1; \Omega), \\ u(x) &\longrightarrow 1 \text{ as } x \longrightarrow K_1 \cap \overline{\Omega} \quad \text{along } p\text{-almost all curves from } \Gamma(K_0, K_1; \Omega). \end{aligned}$$

The  $\mathcal{A}_p$ -capacity of the condenser  $(K_0, K_1; \Omega)$  is defined by

$$\text{cap}_{\mathcal{A}_p}(K_0, K_1; \Omega) = \inf \left\{ \int_{\Omega} |\mathcal{A}\nabla_0 u|^p dx : u \in \mathcal{FC}(K_0, K_1; \Omega) \right\}.$$

*Definition 2.4* Let  $\mathcal{FC}^*(K_0, K_1; \Omega)$  be a class of functions  $u \in ACL_p(\Omega)$ , such that

$$\begin{aligned} u(x) &= 0 \text{ on the intersection of } \Omega \text{ with a neighborhood of } K_0, \\ u(x) &= 1 \text{ on the intersection of } \Omega \text{ with a neighborhood of } K_1. \end{aligned}$$

We define  $\mathcal{A}_p^*$ -capacity by the next value

$$\text{cap}_{\mathcal{A}_p}^*(K_0, K_1; \Omega) = \inf \left\{ \int_{\Omega} |\mathcal{A}\nabla_0 u|^p dx : u \in \mathcal{FC}^*(K_0, K_1; \Omega) \right\}.$$

Let us observe that results from [32, 39] imply that  $ACL_p$ -function is absolutely continuous on  $p$ -almost all horizontal curves. So we can state that an admissible function is an absolutely continuous function on  $p$ -almost all horizontal curves and its horizontal gradient  $|\nabla_0 u|$  belongs to  $L_p(\Omega)$ . Capacities associated with sub-elliptic equations were studied in [4, 6, 7, 11, 12, 21, 34–36].

We give the definition of the  $\mathcal{A}_p$ -module of a system of horizontal vector measures associated with Definitions 2.3 and 2.4. Let  $\zeta(x) = (\zeta_1(x), \dots, \zeta_{n_1}(x))$  be a vector-valued function at each  $x \in \Omega$ ,  $\Omega \in \mathbb{G}$ . If  $\int |\zeta_i| d|\mu_i| < \infty$  for all  $i = 1, \dots, n_1$ , then we define  $\int \zeta \cdot d\mu = \sum_{i=1}^{n_1} \int \zeta_i d\mu_i$ . If  $\zeta$  is such that  $\int \zeta \cdot d\mu \geq 1$  for all  $\mu \in \mathcal{M}$ , then we call  $\zeta$  the admissible (vector-valued) function for the system  $\mathcal{M}$  and write  $\zeta \in \mathcal{FM}(\mathcal{M})$ .

*Definition 2.5* Let  $\xi$  be an admissible vector-valued function and let  $\mu \in \mathcal{M}$  be a complete horizontal vector measure on  $\Omega \subset \mathbb{G}$ . We define the  $\mathcal{A}_p$ -module as

$$M_{\mathcal{A}_p}(\mathcal{M}) = \inf \left\{ \int_{\Omega} |\mathcal{A}\xi|^p dx : \xi \in \mathcal{FM}(\mathcal{M}), \text{ } p\text{-almost everywhere} \right\}.$$

We put the condition  $p$ -almost everywhere to avoid nonsense. For example, let us choose some horizontal vector field  $X_{1j}$ , its orbit  $\beta_i$ , and the one-dimensional Hausdorff measure  $d\beta_i$  on  $\beta_i$ . We fix an arc  $C \subset \beta_i$  of finite length. Let us consider the horizontal vector measure system  $\mathcal{M} = \{(0, \dots, d\beta_i|_C, \dots, 0), (0, \dots, -d\beta_i|_C, \dots, 0)\}$ . There is no admissible vector-valued function  $\xi$  for  $\mathcal{M}$ . However, since  $M_p(|\mathcal{M}|) = 0$ , the  $p$ -exceptional set coincides with  $\mathcal{M}$ , and therefore,  $M_{\mathcal{A}_p}(\mathcal{M}) = 0$ .

*Example 3* If  $\Gamma$  is a family of horizontal curves, then we have, naturally, horizontal vector measures  $d\gamma$ ,  $\gamma \in \Gamma$ , and measures  $|d\gamma| = \langle d\gamma, d\gamma \rangle^{1/2}$ . We write  $d\Gamma = \{d\gamma : \gamma \in \Gamma\}$ , and  $|d\Gamma| = \{|d\gamma| : \gamma \in \Gamma\}$ .

*Example 4* The horizontal gradient of an  $ACL$ -function is another example of a horizontal vector measure. We will work with  $\nabla_0 C^* = \{\nabla_0 u : u \in \mathcal{FC}^*(K_0, K_1; \Omega)\}$ . More generally, for a positive definite  $(N \times N)$ -matrix  $Q(x) = (q_{ij}(x))$  we write

$|Q d\Gamma| = \{ |Q d\gamma| = \langle Q d\gamma, Q d\gamma \rangle^{1/2} : \gamma \in \Gamma \}$  and  $|Q\nabla_0 C^*| = \{ |Q\nabla_0 u| = \langle Q\nabla_0 u, Q\nabla_0 u \rangle^{1/2} : u \in \mathcal{FC}^*(K_0, K_1; \Omega) \}$ .

In [33] we have obtained the next relationships between capacities and modules

$$\text{cap}_{\mathcal{A}_p}^*(K_0, K_1; \Omega) = \text{cap}_{\mathcal{A}_p}(K_0, K_1; \Omega) = M_{\mathcal{A}_p}(d\Gamma) = M_p(|\mathcal{B} d\Gamma|) < \infty. \tag{2.5}$$

If the capacity  $\text{cap}_{\mathcal{A}_p}^*(K_0, K_1; \Omega)$  is strictly positive, then

$$\left( \text{cap}_{\mathcal{A}_p}^*(K_0, K_1; \Omega) \right)^{1/p} \left( M_{B_q}(\nabla_0 C^*) \right)^{1/q} = 1, \quad 1/p + 1/q = 1. \tag{2.6}$$

If  $\text{cap}_{\mathcal{A}_p}^*(K_0, K_1; \Omega) = 0$ , then  $M_{B_q}(\nabla_0 C^*) = \infty$ .

In the present article we study families of measures, that in some sense “separate” compacts  $K_0, K_1 \in \overline{\Omega}$ . We use the definition for a function of bounded variation on homogeneous groups from [3]. In the case  $\mathbb{G} = \mathbb{R}^n$   $X_{1j} = \partial/\partial x_j, j = 1, \dots, n$ , this definition reduces to a classical definition by De Giorgi [13]. Let

$$F(\Omega) = \left\{ \xi(x) = (\xi_1(x), \dots, \xi_{n_1}(x)) : \xi_j(x) \in C_0^1(\Omega), \sup_{x \in \Omega} |\xi(x)| \leq 1 \right\}.$$

For a given  $u \in L_{1,\text{loc}}(\Omega)$  the variation of  $u$  in  $\Omega$  is defined as

$$\text{Var}(u) = \sup \left\{ \int_{\Omega} u(x) \sum_{j=1}^{n_1} X_{1j} \xi_j(x) dx : \xi \in F(\Omega) \right\}.$$

A function  $u$  is said to have *bounded variation* in  $\Omega$  if  $\text{Var}(u) < \infty$ . In this case we shall write  $u \in BV(\Omega)$ . The divergence theorem easily gives the equality  $\text{Var}(u) = \int_{\Omega} |\nabla_0 u(x)| dx$  for functions  $u \in W_1^1(\Omega)$  (see [18]). We shall continue to use the notation  $\nabla_0 u(x)$  for the horizontal distributive gradient of a function of bounded variation. As in [14] one can show that  $\nabla_0 u(x)$  is a vector measure on  $\mathbb{G}$  and  $\text{Var}(u)$  is the total variation of the distributive gradient  $\nabla_0 u(x)$ . If  $E \subset \mathbb{G}$  is measurable, then *the perimeter of  $E$  relative to  $\Omega$*  is defined by  $P(E; \Omega) = \text{Var}(\chi_E)$ , where  $\chi_E$  denotes the characteristic function of  $E$ .

Now we introduce some new families of horizontal vector measures and then formulate relations between them. Let  $\Omega \subset \mathbb{G}$  be a bounded domain. We let  $S = S(K_0, K_1; \Omega)$  be a family of functions  $u \in BV(\Omega)$ , such that

$$\begin{aligned} u(x) &= 0 \text{ on the intersection of } \Omega \text{ with a neighborhood of } K_0, \\ u(x) &= 1 \text{ on the intersection of } \Omega \text{ with a neighborhood of } K_1. \end{aligned}$$

Let  $U \subset \mathbb{G}$  be an open set, such that  $K_1 \subset U, K_0 \cap \overline{U} = \emptyset$ , and  $E = U \cap \Omega$ . We denote by  $\Sigma = \Sigma(K_0, K_1; \Omega)$  the family of characteristic functions  $\chi_E$  of the set  $E \subset \Omega, P(E; \Omega) < \infty$ . We put

$$\begin{aligned} \nabla_0 S &= \left\{ \nabla_0 u : u \in S(K_0, K_1; \Omega) \right\}, & |\nabla_0 S| &= \left\{ |\nabla_0 u| : u \in S(K_0, K_1; \Omega) \right\}, \\ \nabla_0 \Sigma &= \left\{ \nabla_0 \chi_E : \chi_E \in \Sigma(K_0, K_1; \Omega) \right\}, & |\nabla_0 \Sigma| &= \left\{ |\nabla_0 \chi_E| : \chi_E \in \Sigma(K_0, K_1; \Omega) \right\}. \end{aligned}$$

More generally, we set

$$|Q\nabla_0 S| = \left\{ |Q\nabla_0 u| : u \in S(K_0, K_1; \Omega) \right\}, \quad |Q\nabla_0 \Sigma| = \left\{ |Q\nabla_0 \chi_E| : \chi_E \in \Sigma(K_0, K_1; \Omega) \right\},$$

for a positive definite symmetric  $(N \times N)$ -matrix  $Q$ .

**THEOREM 2.1** *Let  $\Omega \subset \mathbb{G}$  be a bounded domain, then*

$$M_{\mathcal{B}_q}(\nabla_0 S) = M_{\mathcal{B}_q}(\nabla_0 \Sigma) = M_q(|\mathcal{A}\nabla_0 S|) = M_q(|\mathcal{A}\nabla_0 \Sigma|) = M_{\mathcal{B}_q}(\nabla_0 C^*) > 0.$$

As a result of Theorem 2.1 and the relations (2.5) and (2.6) we obtain the following reciprocal relations between the extremal length and the extremal width.

**COROLLARY 2.1** *Suppose that  $\mathcal{B}$  is uniformly continuous in a bounded domain  $\Omega \subset \mathbb{G}$ ,  $1/p + 1/q = 1$ , and  $\Gamma$  is the family of curves (2.4). If  $M_{\mathcal{A}_p}(d\Gamma) = 0$ , then  $M_{\mathcal{B}_q}(\nabla_0 \Sigma) = \infty$ . If  $M_{\mathcal{A}_p}(d\Gamma) > 0$ , then*

$$\left( M_{\mathcal{A}_p}(d\Gamma) \right)^{1/p} \left( M_{\mathcal{B}_q}(\nabla_0 \Sigma) \right)^{1/q} = 1.$$

If  $\mathcal{A} = \mathcal{B}$  are the identity matrix, then we get

**COROLLARY 2.2** *Let  $\Omega$  be a bounded domain and  $1/p + 1/q = 1$ . If  $M_p(|d\Gamma|) = 0$ , then  $M_q(|\nabla_0 \Sigma|) = \infty$ . If  $M_p(|d\Gamma|) > 0$ , then  $(M_p(|d\Gamma|))^{1/p} (M_q(|\nabla_0 \Sigma|))^{1/q} = 1$ .*

### 3. PRELIMINARY RESULTS

By definition, the  $M_{\mathcal{A}_p}(\mathcal{M})$  is monotone. For the completeness we give the proof of the next property (see also [2, 46]).

**LEMMA 3.1** *Let  $\mathcal{M}_i$  be an increasing sequence of horizontal vector measures, such that  $\mathcal{M} = \bigcup_{i=1}^{\infty} \mathcal{M}_i$ . Then  $\lim_{i \rightarrow \infty} M_{\mathcal{A}_p}(\mathcal{M}_i) = M_{\mathcal{A}_p}(\mathcal{M})$ .*

*Proof* Let us denote by  $c$  the limit of  $M_{\mathcal{A}_p}(\mathcal{M}_i)$  as  $i \rightarrow \infty$ . It is sufficient to show that  $M_{\mathcal{A}_p}(\mathcal{M}) \leq c$ . Fix  $\varepsilon > 0$ . There exists  $\xi_i \in \mathcal{FM}(\mathcal{M}_i)$ , such that

$$M_{\mathcal{A}_p}(\mathcal{M}_i) \leq \int_{\Omega} |\mathcal{A}\xi_i|^p dx \leq M_{\mathcal{A}_p}(\mathcal{M}_i) + \varepsilon \tag{3.1}$$

for  $p$ -almost all  $\mu \in \mathcal{M}$  and for each  $i \in \mathbb{N}$ . Since  $(\xi_i + \xi_k)/2 \in \mathcal{FM}(\mathcal{M}_i)$   $p$ -almost everywhere for  $i \leq k$ , we also have  $M_{\mathcal{A}_p}(\mathcal{M}_i) \leq \int_{\Omega} |\mathcal{A}((\xi_i + \xi_k)/2)|^p dx$ . The sequence  $\{\xi_i\}$  is a Cauchy sequence in  $L_p(\Omega)$ , because of

$$\begin{aligned} \int_{\Omega} \left| \frac{\xi_i - \xi_k}{2} \right|^p dx &\leq \alpha \int_{\Omega} \left| \mathcal{A} \frac{\xi_i - \xi_k}{2} \right|^p dx \\ &\leq \alpha \left( \frac{1}{2} \int_{\Omega} |\mathcal{A}\xi_i|^p dx + \frac{1}{2} \int_{\Omega} |\mathcal{A}\xi_k|^p dx - \int_{\Omega} \left| \mathcal{A} \frac{\xi_i + \xi_k}{2} \right|^p dx \right) \rightarrow 0. \end{aligned}$$

We used (2.3) and Clarkson’s inequalities. Therefore, the sequence  $\{\xi_i\}$  tends to some  $\xi$  in  $L_p(\Omega)$  with  $\int_{\Omega} |\mathcal{A}\xi|^p dx = c$  by (3.1). By a property of measure system we can find a subsequence  $\{\xi_{i_m}\}$ , such that  $\int |\xi - \xi_{i_m}| |d\mu| \rightarrow 0$  for  $p$ -almost all  $\mu \in \mathcal{M}$  [17 Theorem 3 (f)]. This implies that  $\int (\xi - \xi_{i_m}) \cdot d\mu \rightarrow 0$   $p$ -almost everywhere and

$$\int \xi \cdot d\mu = \int \xi_{i_m} \cdot d\mu + \int (\xi - \xi_{i_m}) \cdot d\mu \geq \liminf \int \xi_i \cdot d\mu \geq 1 \quad \text{for } p\text{-a.a. } \mu \in \mathcal{M}.$$

Since  $\xi \in \mathcal{FM}(\mathcal{M})$ , finally, we obtain  $M_{\mathcal{A}_p}(\mathcal{M}) \leq \int_{\Omega} |\mathcal{A}\xi|^p dx = c$ . ■

For a moment, let us denote by  $F$  one of the sets  $C^*$ ,  $S$ ,  $\Sigma$ , and by  $\nabla_0 F$  one of the sets  $\nabla_0 C^*$ ,  $\nabla_0 S$ ,  $\nabla_0 \Sigma$ , respectively.

**COROLLARY 3.1** *Let  $K_0, K_1 \subset \Omega$  be disjoint compacts and let  $K_0^i, K_1^i \in \Omega$  be sequences of compact sets, such that  $K_0^0 \cap K_1^0 = \emptyset$ ,  $K_0^{i+1} \subset \text{int } K_0^i$ ,  $K_1^{i+1} \subset \text{int } K_1^i$ ,  $K_0 = \bigcap_{i=0}^{\infty} K_0^i$ ,  $K_1 = \bigcap_{i=0}^{\infty} K_1^i$ . Then,  $M_{\mathcal{A}_p}(\nabla_0 F(K_0, K_1; \Omega)) = \lim_{i \rightarrow \infty} M_{\mathcal{A}_p}(\nabla_0 F(K_0^i, K_1^i; \Omega))$ .*

*Proof* Since the measure system  $\nabla_0 F(K_0^i, K_1^i; \Omega)$  is increasing and  $\nabla_0 F(K_0, K_1; \Omega) = \bigcup_i \nabla_0 F(K_0^i, K_1^i; \Omega)$ , Corollary 3.1 follows from Lemma 3.1. ■

**LEMMA 3.2** *Let  $\Omega_0$  be an open subset of  $\Omega$ , such that  $K_0, K_1 \subset \overline{\Omega}_0$ . Then,*

$$M_{\mathcal{A}_p}(\nabla_0 F(K_0, K_1; \Omega)) \leq M_{\mathcal{A}_p}(\nabla_0 F(K_0, K_1; \Omega_0)). \tag{3.2}$$

*Proof* If  $M_{\mathcal{A}_p}(\nabla_0 F(K_0, K_1; \Omega_0)) = \infty$ , then there is nothing to prove. Let us assume that the right-hand side of (3.2) is finite and  $\xi \in \mathcal{FM}(\nabla_0 F(K_0, K_1; \Omega_0))$ . We note that if  $u \in F(K_0, K_1; \Omega)$ , then  $u|_{\Omega_0} \in F(K_0, K_1; \Omega_0)$ . The function

$$\eta(x) = \begin{cases} \xi(x) & \text{if } x \in \Omega_0, \\ 0 & \text{otherwise} \end{cases}$$

is admissible for  $M_{\mathcal{A}_p}(\nabla_0 F(K_0, K_1; \Omega))$  in view of  $\int_{\Omega} \eta \cdot \nabla_0 u = \int_{\Omega_0} \xi \cdot \nabla_0(u|_{\Omega_0}) \geq 1$ . Hence,

$$M_{\mathcal{A}_p}(\nabla_0 F(K_0, K_1; \Omega)) \leq \int_{\Omega} |\mathcal{A}\eta|^p dx = \int_{\Omega_0} |\mathcal{A}\xi|^p dx.$$

Taking the infimum with respect to  $\xi \in \mathcal{FM}(\nabla_0 F(K_0, K_1; \Omega_0))$ , we obtain (3.2). ■

**LEMMA 3.3** *Let  $K_0, K_1 \subset \Omega_0 \subset \overline{\Omega}_0 \subset \Omega$ . There is a sequence of open sets  $\Omega_0 \subset \Omega_1 \subset \overline{\Omega}_1 \subset \dots \subset \tilde{\Omega} \subset \Omega$ , such that*

$$\lim_{i \rightarrow \infty} M_{\mathcal{A}_p}(\nabla_0 F(K_0, K_1; \Omega_i)) = M_{\mathcal{A}_p}(\nabla_0 F(K_0, K_1; \tilde{\Omega})). \tag{3.3}$$

*Proof* We choose a positive monotone function  $r < d_c(\Omega_0, \Omega)$  that tends to 0. The sequence of sets  $\Omega(r) = \{x \in \Omega: d_c(x, \partial\Omega) > r\}$  exhausts  $\Omega$  as  $r \rightarrow 0$ . Since  $m(r) = M_{\mathcal{A}_p}(\nabla_0 F(K_0, K_1; \Omega(r)))$  is a non-decreasing function, it is continuous from the right

except for some countable set of  $r$ . Therefore, there is a value  $r = \tilde{r} > 0$ , such that  $\lim_{r \rightarrow \tilde{r}} m(r) = m(\tilde{r})$ . We put  $\tilde{\Omega} = \Omega(\tilde{r})$  and complete the proof.  $\blacksquare$

From now on, we will say that  $\tilde{\Omega}$  can be approximated from inside with respect to the module  $M_{\mathcal{A}_p}(\nabla_0 F(K_0, K_1; \tilde{\Omega}))$  if  $\tilde{\Omega}$  satisfies (3.3).

LEMMA 3.4 *Let  $K_0, K_1 \subset \Omega$  and the domain  $\Omega$  can be approximated from inside with respect to the module  $M_{\mathcal{A}_p}(\nabla_0 C^*(K_0, K_1; \Omega))$ . Then,*

$$M_{\mathcal{A}_p}(\nabla_0 \Sigma(K_0, K_1; \Omega)) \leq M_{\mathcal{A}_p}(\nabla_0 S(K_0, K_1; \Omega)) \leq M_{\mathcal{A}_p}(\nabla_0 C^*(K_0, K_1; \Omega)). \tag{3.4}$$

*Proof* The first inequality of (3.4) is a consequence of the inclusion  $\nabla_0 \Sigma \subset \nabla_0 S$ . To prove the second one we fix  $\varepsilon > 0$ . The condition of the theorem implies that there is  $\hat{\Omega} \subset \Omega$ , such that

$$M_{\mathcal{A}_p}(\nabla_0 C^*(K_0, K_1; \hat{\Omega})) \leq M_{\mathcal{A}_p}(\nabla_0 C^*(K_0, K_1; \Omega)) + \varepsilon. \tag{3.5}$$

We can find compact sets  $K_0^0, K_1^0 \subset \Omega$  that possesses the inequality

$$M_{\mathcal{A}_p}(\nabla_0 S(K_0, K_1; \Omega)) \leq M_{\mathcal{A}_p}(\nabla_0 S(K_0^0, K_1^0; \Omega)) + \varepsilon \tag{3.6}$$

by Corollary 3.1. If we prove

$$M_{\mathcal{A}_p}(\nabla_0 S(K_0^0, K_1^0; \Omega)) \leq M_{\mathcal{A}_p}(\nabla_0 C^*(K_0, K_1; \hat{\Omega})), \tag{3.7}$$

then the second inequality of 3.4 will follow from (3.5)–(3.7) by arbitrariness of  $\varepsilon$ .

To show (3.7) we take the domain  $\tilde{\Omega} = \{x \in \Omega: d_c(x, \partial\Omega) > (1/2)d_c(\partial\tilde{\Omega}, \partial\Omega)\}$  and a positive number  $r < \min\{(1/2)d_c(\partial\tilde{\Omega}, \partial\Omega), d_c(\partial K_0, \partial K_0^0), d_c(\partial K_1, \partial K_1^0)\}$ . We choose a function  $\xi \in \mathcal{FM}(\nabla_0 C^*(K_0, K_1; \hat{\Omega}))$  and define

$$\eta(x) = \begin{cases} \xi(x) & \text{if } x \in \hat{\Omega}, \\ 0 & \text{otherwise.} \end{cases}$$

Let  $\eta_r(x) = \int_{B(0,1)} \eta(x\delta_r y) \psi(y) dy$ , where  $\psi(y)$  is a non-negative  $C^\infty$ -function supported in  $B(0, 1)$ . The function  $\eta_r$  belongs to  $C_0^\infty(\tilde{\Omega})$  by definition and we also claim

$$\eta_r \in \mathcal{FM}(\nabla_0 C^*(K_0^0, K_1^0; \Omega)) \quad \text{and} \quad \eta_r \in \mathcal{FM}(\nabla_0 S(K_0^0, K_1^0; \Omega)). \tag{3.8}$$

We note that if  $u(x) \in \mathcal{FC}^*(K_0^0, K_1^0; \Omega)$ , then  $u(x(\delta_r y)^{-1})|_{\tilde{\Omega}} \in \mathcal{FC}^*(K_0, K_1; \hat{\Omega})$  for  $|y| \leq 1$ . Hence,

$$\begin{aligned} \int_{\Omega} \eta_r(x) \nabla_0 u(x) dx &= \int_{B(0,1)} \psi(y) dy \int_{\Omega} \eta(x\delta_r y) \nabla_0 u(x) dx \\ &= \int_{B(0,1)} \psi(y) dy \int_{\tilde{\Omega}} \xi(x) \nabla_0 u(x(\delta_r y)^{-1}) dx \geq 1 \end{aligned}$$

and the first assertion of (3.8) is obtained.

To show the second statement of (3.8), we choose  $u \in S(K_0^0, K_1^0; \Omega)$ . In [18] it was proved that for  $u \in BV(\Omega)$  there exists a sequence  $\{u_k\}_{k \in \mathbb{N}}$  in  $C^\infty(\Omega)$ , such that the following holds:  $\lim_{k \rightarrow \infty} \|u_k - u\|_{L^1(\Omega)} = 0$ ,  $\lim_{k \rightarrow \infty} \text{Var}(u_k, \Omega) = \text{Var}(u, \Omega)$ , and  $\int_\Omega \varphi \cdot \nabla_0 u_i dx \rightarrow \int_\Omega \varphi \cdot \nabla_0 u$  for any vector-valued function  $\varphi \in C_0^\infty(\Omega)$ . Obviously, we can find  $u_k$  that vanishes in some neighborhood of  $K_0^0$  and  $u_k = 1$  in a neighborhood of  $K_1^0$ .

We should consider two options. If  $\nabla_0 u_k \in L_p(\Omega)$ , then  $u_k \in \mathcal{FC}^*(K_0^0, K_1^0; \Omega)$  and

$$1 \leq \lim_{k \rightarrow \infty} \int_\Omega \eta_r \nabla_0 u_k dx = \int_\Omega \eta_r \cdot \nabla_0 u$$

by the first assertion of (3.8). The horizontal vector measure  $\nabla_0 u$  does not need to be absolutely continuous with respect to  $dx$ . This proves the second relation of (3.8). Now, we can conclude that  $M_{\mathcal{A}_p}(\nabla_0 S(K_0^0, K_1^0; \Omega)) \leq \int_\Omega |\mathcal{A}\eta_r|^p dx$ . Letting  $r \rightarrow 0$ , we obtain the inequality  $M_{\mathcal{A}_p}(\nabla_0 S(K_0^0, K_1^0; \Omega)) \leq \int_\Omega |\mathcal{A}\eta|^p dx = \int_{\tilde{\Omega}} |\mathcal{A}\xi|^p dx$ . Taking the infimum with respect to  $\xi \in \mathcal{FM}(\nabla_0 C^*(K_0, K_1; \tilde{\Omega}))$  we complete the lemma in this case.

If  $\nabla_0 u_k \notin L_p(\Omega)$ , then we take a function  $v \in C_0^\infty(\Omega)$ ,  $0 \leq v \leq 1$  in  $\Omega$ , and  $v = 1$  in  $\tilde{\Omega}$ . Since  $vu_k \in C_0^\infty(\Omega)$  we obtain  $vu_k \in \mathcal{FC}^*(K_0^0, K_1^0; \Omega)$  and complete the lemma as above. ■

#### 4. PROOF OF THEOREM 2.1

To prove Theorem 2.1 we will show four inequalities:

$$M_{B_q}(\nabla_0 S) \leq M_{B_q}(\nabla_0 C^*), \tag{4.1}$$

$$M_q(|\mathcal{A}\nabla_0 \Sigma|) \geq M_{B_q}(\nabla_0 C^*), \tag{4.2}$$

$$M_{B_q}(\nabla_0 S) \geq M_q(|\mathcal{A}\nabla_0 S|) \geq M_q(|\mathcal{A}\nabla_0 \Sigma|), \tag{4.3}$$

$$M_{B_q}(\nabla_0 S) \geq M_{B_q}(\nabla_0 \Sigma) \geq M_q(|\mathcal{A}\nabla_0 \Sigma|). \tag{4.4}$$

We start with the first one. Let  $K_0^i, K_1^i$  be sequences of compacts, such that  $K_0^0 \cap K_1^0 = \emptyset$ ,  $K_0^{i+1} \subset \text{int } K_0^i$ ,  $K_1^{i+1} \subset \text{int } K_1^i$ ,  $K_0 = \bigcap_{i=0}^\infty K_0^i$ ,  $K_1 = \bigcap_{i=0}^\infty K_1^i$ , and let  $\Omega^i = \Omega \cup (\text{int } K_0^i) \cup (\text{int } K_1^i)$ . Let us show  $\bigcup_{i=1}^\infty \nabla_0 S(K_0^i, K_1^i; \Omega^i) = \nabla_0 S(K_0, K_1; \Omega)$ . Really, if  $u \in S(K_0^i, K_1^i; \Omega^i)$ , then  $u \in S(K_0^{i+1}, K_1^{i+1}; \Omega^{i+1})$  and  $u \in S(K_0, K_1; \Omega)$ . Moreover,  $\text{supp}(\nabla_0 u)|_{(\Omega^i)} \subset \Omega^i \setminus (K_0^i \cup K_1^i) \subset \Omega$ . Thus,  $\nabla_0 S(K_0^i, K_1^i; \Omega^i)$  is increasing and  $\bigcup_{i=1}^\infty \nabla_0 S(K_0^i, K_1^i; \Omega^i) \subset \nabla_0 S(K_0, K_1; \Omega)$ . Now, we take  $u \in S(K_0, K_1; \Omega)$  and note that for sufficiently big  $i \in \mathbb{N}$  the function  $u$  belongs to  $S(K_0^i, K_1^i; \Omega^i)$ . We put

$$v = \begin{cases} u & \text{if } x \in \Omega, \\ 0 & \text{if } x \in \text{int } K_0^i, \\ 1 & \text{if } x \in \text{int } K_1^i, \end{cases}$$

then  $v \in S(K_0^i, K_1^i; \Omega^i)$ ,  $\text{supp}(\nabla_0 v)|_{\Omega^i} = \text{supp}(\nabla_0 u)|_{\Omega}$ . Hence, the reverse inclusion also holds and  $\lim_{i \rightarrow \infty} M_{\mathcal{B}_q}(\nabla_0 S(K_0^i, K_1^i; \Omega^i)) = M_{\mathcal{B}_q}(\nabla_0 S(K_0, K_1; \Omega))$  by Lemma 3.1.

We have  $M_{\mathcal{B}_q}(\nabla_0 S(K_0^i, K_1^i; \Omega^i)) \leq M_{\mathcal{B}_q}(\nabla_0 S(K_0, K_1; \Omega^i))$  in view of the inclusion  $S(K_0^i, K_1^i; \Omega^i) \subset S(K_0, K_1; \Omega^i)$ . Let us observe that since  $K_0, K_1 \subset \Omega^i$ , we may modify  $\Omega^i$  such, that  $\Omega^i$  can be approximated from inside with respect to the module  $M_{\mathcal{B}_q}(\nabla_0 C^*(K_0, K_1; \Omega^i))$ . Lemma 3.4 implies

$$M_{\mathcal{B}_q}(\nabla_0 S(K_0, K_1; \Omega^i)) \leq M_{\mathcal{B}_q}(\nabla_0 C^*(K_0, K_1; \Omega^i)).$$

Finally, we conclude

$$\begin{aligned} M_{\mathcal{B}_q}(\nabla_0 S(K_0, K_1; \Omega)) &= \lim_{i \rightarrow \infty} M_{\mathcal{B}_q}(\nabla_0 S(K_0^i, K_1^i; \Omega^i)) \leq \lim_{i \rightarrow \infty} M_{\mathcal{B}_q}(\nabla_0 S(K_0, K_1; \Omega^i)) \\ &\leq \lim_{i \rightarrow \infty} M_{\mathcal{B}_q}(\nabla_0 C^*(K_0, K_1; \Omega^i)) \leq M_{\mathcal{B}_q}(\nabla_0 C^*(K_0, K_1; \Omega)), \end{aligned}$$

where the last inequality follows from  $\Omega \subset \Omega^i$ .

Now, we start to prove (4.2). In view of (2.6) is it sufficient to show that the capacity  $\text{cap}_{\mathcal{A}_p}^*(K_0, K_1; \Omega)$  is strictly positive and  $\left(\text{cap}_{\mathcal{A}_p}^*(K_0, K_1; \Omega)\right)^{1/p} (M_q(|\mathcal{A}\nabla_0 \Sigma|))^{1/q} \geq 1$ . Let  $u \in \nabla_0 C^*$  and  $0 \leq u \leq 1$ . In this case  $u \in W_1^1(\Omega)$  and inclusion  $W_1^1(\Omega) \subset BV(\Omega)$  (see [18]) implies  $u \in BV(\Omega)$ . We put  $E_t = \{x \in \Omega : u(x) > t\}$ . In [18] it was proved that  $\chi_{E_t} \in BV(\Omega)$  for almost all  $t$ . We will use the co-area formula for homogeneous groups [22,38]

$$\int_{\Omega} f(x)|\nabla_0 u| dx = \int_0^1 \int_{\{u=t\}} u(y)|n_0| dS dt,$$

where  $f(x)$  is a non-negative measurable function,  $n_0$  is the horizontal component of the unit normal to  $\{u = t\}$  and  $dS$  is the Riemannian area element on  $\{u = t\}$ . In our case  $n_0 dS = \nabla_0 \chi_{E_t}$  and  $|n_0| = |\nabla_0 u|/|\nabla u|$ . Let us take  $\rho \in \mathcal{FM}(|\mathcal{A}\nabla_0 \Sigma|)$ . Then  $\int_{\{u=t\}} \rho |\mathcal{A}\nabla_0 \chi_{E_t}| dS \geq 1$  for almost all  $t$ . Hence, the co-area formula yields

$$\begin{aligned} 1 &\leq \int_0^1 \int_{\{u=t\}} \rho |\mathcal{A}\nabla_0 \chi_{E_t}| dS dt = \int_0^1 \int_{\{u=t\}} \rho \frac{|\mathcal{A}\nabla_0 u| |\nabla_0 u|}{|\nabla u| |\nabla_0 u|} dS dt \\ &= \int_{\Omega} \rho(x) |\mathcal{A}\nabla_0 u| dx \leq \left( \int_{\Omega} |\mathcal{A}\nabla_0 u|^p dx \right)^{1/p} \left( \int_{\Omega} \rho^q dx \right)^{1/q}. \end{aligned}$$

Taking the infimum with respect to  $u \in \nabla_0 C^*$  and  $\rho \in \mathcal{FM}(|\mathcal{A}\nabla_0 \Sigma|)$  we obtain the required inequality.

We will prove (4.3). The second inequality follows from the inclusion  $\mathcal{A}\nabla_0 \Sigma \subset \mathcal{A}\nabla_0 S$ . To show the first one, we choose  $\xi \in \mathcal{FM}(\nabla_0 S)$  and will obtain that  $\mathcal{B}\xi \in \mathcal{FM}(\mathcal{A}\nabla_0 S)$ . The inequality  $\int \xi \cdot \nabla_0 u \geq 1$  holds for all  $\nabla_0 u \in \nabla_0 S$  except for some family  $\mathcal{U} \subset \nabla_0 S$  with  $M_q(|\mathcal{U}|) = 0$ . We state that  $M_q(|\mathcal{U}|) = 0$  implies  $M_q(|\mathcal{A}\mathcal{U}|) = 0$ . For given  $\varepsilon > 0$  we can find non-negative  $\rho \in \mathcal{FM}(|\mathcal{U}|)$ , such that  $\int \rho^q dx \leq \varepsilon$ . Then,  $1 \leq \int \rho |\nabla_0 u| \leq \alpha \int \rho |\mathcal{A}\nabla_0 u|$  by (2.3) for  $\nabla_0 u \in \mathcal{U}$  and we conclude that  $\alpha \rho \in \mathcal{FM}(|\mathcal{A}\mathcal{U}|)$ . Finally,

we have  $M_q(|\mathcal{A}u|) \leq \int (\alpha\rho)^q dx \leq (\alpha)^q \varepsilon$  that proves  $M_q(|\mathcal{A}u|) = 0$ . Since we have

$$1 \leq \int_{\Omega} \xi \cdot \nabla_0 u = \int_{\Omega} \mathcal{B}\xi \cdot \mathcal{A}\nabla_0 u \leq \int_{\Omega} |\mathcal{B}\xi| |\mathcal{A}\nabla_0 u|,$$

we conclude, that  $|\mathcal{B}\xi|$  belongs to  $\mathcal{FM}(|\mathcal{A}\nabla_0 S|)$   $q$ -almost everywhere. Therefore,

$$M_q(|\mathcal{A}\nabla_0 S|) \leq \int_{\Omega} |\mathcal{B}\xi|^q dx.$$

Taking the infimum with respect to  $\xi \in \mathcal{FM}(\nabla_0 S)$  we obtain the first inequality of (4.3).

The proof of the statement (4.4) is similar. Theorem 2.1 is complete.

## 5. PROOF OF COROLLARIES 2.1 AND 2.2

Theorem 2.1 gives  $M_{\mathcal{B}_q}(\nabla_0 C^*) = M_{\mathcal{B}_q}(\nabla_0 \Sigma)$ . We obtain  $\text{cap}_{\mathcal{A}_p}^*(K_0, K_1; \Omega) = M_{\mathcal{A}_p}(d\Gamma)$  from (2.5). These equalities and relation (2.6) prove Corollary 2.1.

To show Corollary 2.2, we note that if  $\mathcal{A}, \mathcal{B}$  are unity matrices, then (2.5) and Theorem 2.1 imply  $M_p(d\Gamma) = M_p(|d\Gamma|)$  and  $M_q(\nabla_0 \Sigma) = M_q(|\nabla_0 \Sigma|)$ , respectively. From this and Corollary 2.1 we obtain Corollary 2.2.

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